

PRODUCT CATALOG

Shenzhen Han's Robot Co., Ltd.

400-852-9898

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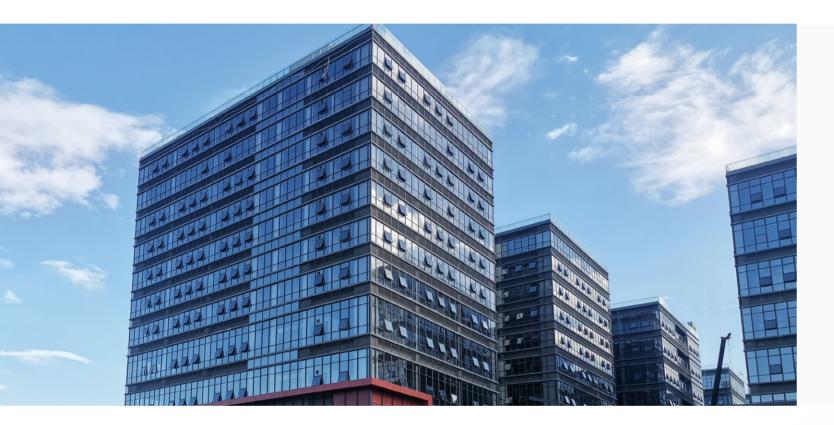




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Company Profile



Vision To be the global leader in the era of intelligent robots

Serve humanity with

Han's Robot is a national high-tech enterprise and a national-level specialised and innovative SME that is incubated based on the research and development team of over 100 people at Han's Robot Research Institute, which is invested by Han's Laser Technology Industry Group Co., Ltd. The company was established in September 2017 and has production and R & D bases in Foshan and Shenzhen, as well as subsidiaries and offices in Tianjin, Wuxi, Chengdu and Stuttgart, Germany. The company is committed to the research, development, promotion and application of intelligent collaborative robots in the fields of industry, healthcare, logistics, education and service, and aims to become a global leader in the era of intelligent robots.

(2) Mission

robot technology

Values

Lead, fast-speed, service, sharing, passion, enthusiasm, curiosity

Global Service Network

Partners from more than **100+** countries & regions

China, South Korea, Japan, Thailand, Singapore, Malaysia, Australia, New Zealand, the United States, Canada, Mexico, Brazil, Colombia, Argentina, Russia, Britain, France, Germa- ny, Spain, the Netherlands, Italy, etc.

Top talents from 25+ countries & regions

200+ 25+ 500+ Employees Professional Countries & regions engineers

Creating a global full-industry chain ecosystem cluster

Based on Global Intelligent Manufacturing Center (Foshan) of Han's Robot a full-industry chain ecosystem cluster centered on collaborative robots has been, formed, aiming to build a national-level digital intelligent manufacturing demonstration benchmark park.

Milestones





October 2022 Han's Robot Global Intelligent Manufacturing Center was established.

June 2022 Subsidiary in Chengdu City was established

Han's Robo The Unique Advantages of Collaborative Robots Products

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Han's Robot has indepenently developed its own advanced collaborative robots technology, which is constantly expanding the breadth and depth of serving humanity. Its products covers the needs of different customers, with different load capacities ranging from 3KG to 20KG. Product development has progressed from the first generation of 6-axis collaborative robot (Elfin series) to the higher performance third generation (Elfin-Pro series).



Full Independence and Control of Core Components



Unique Dual Module Set



With EtherCAT Bus



All Joint Ranges of Motion up to $\pm 360^{\circ}$



HAN'S ROBOT

Multi-terminal Graphical Control

Motors, servo drives	\oslash
Optical encoders	\oslash
Six-dimensional force/torque sensors	\oslash
Electromagnetic brakes, high-speed inverters	\oslash

The first dual-joint module in China	\oslash
Unique arm design and singularity optimization	\oslash
Higher integration, higher flexibility	\oslash

High immunity to interference	\oslash
High communication frequency and speed	\oslash
High level of safety and precise movement trajectory	\oslash
Fast docking to third party controllers	\oslash

Achieving a range of motion of $\pm 360^\circ$ in each joint	\oslash
Ensuring that the end reaches more and more difficult positions	\oslash
High flexibility, high efficiency of movement and low power consumption	\oslash
Enables more possibilities for production	\oslash

Support for handheld demonstrators, tablets, computers and other terminals	\oslash
Graphical programming, intuitive and easy to understand	\oslash
User-friendly interactive design	\oslash



IP66 Protection Class

\oslash
\oslash
\oslash
\oslash





Cleanliness to ISO 5

Excellent surface cleanliness of the entire machine and optimised structure of the internal components

 \oslash

 \oslash

ISO 5 certified cleanliness

Aerospace industrial standard for long-term 📀 use





Explosion-proof Certification

- Certified by the national instrumentation explosion- proof safety inspection station
- Can be used for special operations in explosive \bigcirc and combustible dust environments



Innovative Ways of Holding the Gate

Short braking distances and short braking times thanks to electromagnetic brakes

 \oslash

 \oslash

In the event of collision with people/objects, emergency stop, power failure, etc., the robot's posture will immediately lock in place and the braking distance will be zero sliding

Zero power on and off displacement

More Open Platform

Rich software interface available		
Full support for ROS systems	\oslash	
Meeting the needs of users for integrated development etc.	\oslash	

10+ Years of Accumulated Industrial Experience

More than 10 years of experience in motors			
servers and motion control based on Han's Robot Research Institute team	\oslash		
Long-term partnerships with universities in China	\oslash		
and abroad to explore collaborative robots technology and applications	Ø		

Han's Robot Plug & Play Tools

Adhering to the ecological concept of "all are friends in the world", Han's Robot has created a more complete and open collaborative ecosystem, and designed various IO and communication interfaces. These IO interfaces greatly expand the application scope of the robot and can support "plug and play" with most accessories in the industrial ecosystem, such as grippers, vision, and sensors, which can meet the needs of multiple scenarios such as loading and unloading, assembly, testing, handling, screw driving, grinding, spraying etc.

Grippers

 \bigcirc^{\dagger}



Force Sensor

Vision

483

Link-touch

Micromatch

Mech-Mind

Keyence

ATI

G	Onrobot
∂ 20000 2000	Hypersen
	Cosmosvision
FT	Seizet
	UBSense



The "POSS" Concept

The most reliable body & the most intelligent brain

Han's Robot believes that the characteristics of a good collaborative robots can be summarised as **POSS**, and it is delicated to the research and application expression of top-notch robotics, developing robots with the most reliable body and the most intelligent brain.









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Han's Robot **Product Overview** →



Elfin-Pro Collaborative Robot

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Han's Robot Products / More Cost-Effective

Elfin Collaborative Robot

Overview 概述

The Elfin collaborative robot can be used in automated integrated production lines, assembly, picking, welding, grinding, spraying and other applications, and has been exported to more than 100 countries and regions. It adopts a unique double-joint module design, where one motion module contains two joints to form a unique kinematic structure, which not only differs from most collaborative robots on the market, but also provides more flexibility when working.



亮点 Why Elfin

Optimized singularity

The unique arm design not onlyavoids the product homogeneity, but also reduces the singularity



First dual-joint module design in China

The unique kinematic design enables the robot to have high flexibility. The highly integrated modular design minimizes the arm weight



Highly flexible 6-DOF collaborative robot

The collaborative robot with 4/6-axis coaxial structure has almost reached the flexibility of 7-DOF robots



Modularity

All-in-one module of fully self-developed reducer, motor, encoder, drive and software







• Automotive

• Semiconductor

• Metal processing

• Education and research

joint motions:



J6

J5

J4

J3

J2

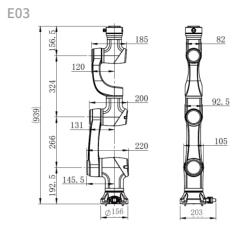
J1



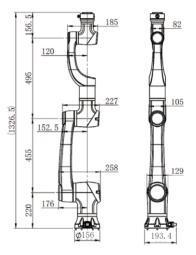
Technical Specifications

Model	E03	E05	E05-L	E10	E10-L	E15	
Weight	18kg	25kg	26kg	43kg	45kg	60kg	
Payload	3kg	5kg	3.5kg	10kg	8kg	15kg	
Reach	590mm	800mm	950mm	1000mm	1300mm	1300mm	
Power Consumption	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application	600W typical applicatior	
Joint Range			±3	60°			
Joint Speed	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 80°/s J3-J4 120°/s J5-J6 150°/s	
Tool Speed			2m	n/s			
Repeatability	±0.02mm	±0.02mm	±0.02mm	±0.03mm	±0.03mm	±0.05mm	
Degree Of Freedom			(ô			
End I/O Port		Digital input: 3, digital output: 3, analog input: 2					
Control box I/O port		Digital input: 16	, digital output: 16	, analog input: 2, a	nalog output: 2		
I/O Source			24	/ 2A			
Communication		TCP/IP, ModbusTCP, Profinet (Optional), Ethernet/IP (Optional)					
Programming		Grap	hical programmin	g, remote call inter	face		
IP Classification		IP54					
Collaborative Operation	٦	10 advanced security configuration functions					
Main Material	Aluminum alloy						
Working Temperature	0-50°C						
Power input	200-240V AC, 50-60Hz						
Cable		Cable to the control box: 5m; cable to the teach pendant: 5m					

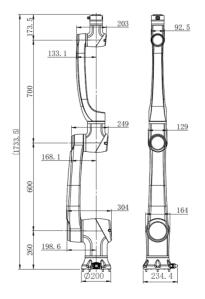
Drawing



E05-L

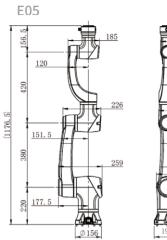






Control Box		Mini Control Box (Opt	ional)	Teach Pendant	
Dimensions 44	15.2mm x 318.8mm x (360+176)mm	Dimensions	323x221x80(mm)	Dimensions 32	?7 mm x 230 mm x (45+22) mm
Stand Height	176mm	Power Input	DC30~60V	Weight	2.7kg (Include Cable)
Weight	18.5kg	I/O Source	DC24V	Display	10.4"
Power Output	48V DC	I/O Port	Inputs 8 , Outputs 8	Resolution	1024 x 800
Working Temperature	0~50°C	IP Classification	IP20	E-stop Button	1
Working Humidity 90%	6 Relative Humidity (non-condensing)	Communication	TCP/IP Modbus	IP Classification	IP54
IP Classification	IP20				

E10-L

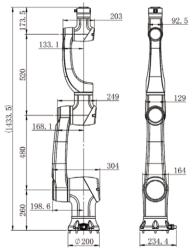




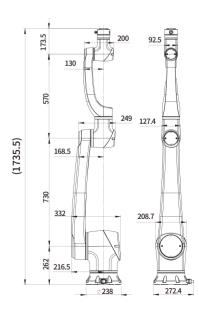
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E10



E15



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Han's Robot Products / More Performance

Elfin-Pro Collaborative Robot

Overview

The Elfin Pro series collaborative robots are developed on the basis of the Elfin series, which continues the advantages of the Elfin series such as complete product models, easy deployment, high precision, high flexibility and dual-joint module design, modular design, etc. At the same time, the product's capabilities are newly upgraded, integrating cutting-edge AI technology, realizing the integration of end force control and end vision, and adopting a new surface treatment process, which is both beautiful and practical, achieving more stable and reliable performance, safer human-robot collaboration and wider application scenarios.



Why Elfin-Pro

Force Control Integration

Internal alignment, strong antiinterference capability, constant force control for trajectory following and fast programming; smooth control, smooth dragging of the demonstrator;force-controlled probing,intelligent assembly, enabling small-batch, multi-variety flexible production.



Visual Integration

Internal alignment for high interference immunity and fast deployment. With visual positioning, visual classification recognition, the object detection, QR code recognition and other AI application capabilities; based on Han's Robot's self-developed hardware and software platform, easy to operate, pretty interactive and scalable.



Higher Protection Wider Application

IP66 level of protection, which can be adapted to di fferent production environments, further extending the application scenarios of collaborative robots



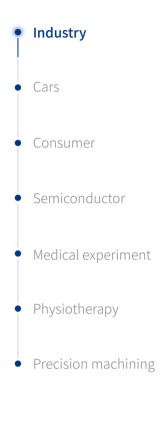
High Sensitivity High Security

joint motions:

The entire machine realizes 1000Hz real-time control refresh frequency, which can achieve the industry-leading trajectory precision control, stable and reliable performance, faster resp onse time and safer human-machine collabora tion







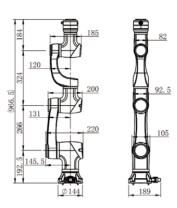
Application • Welding Massage • Polishing • Grinding Assembly • Screen inspection



	Model	E03-Pro	E05-Pro	E05L-Pro	E10-Pro	E10L-Pro	
	Weight	18kg	25kg	26kg	43kg	45kg	
	Payload	3kg	5kg	3.5kg	10kg	8kg	
	Reach	590mm	800mm	950mm	1000mm	1300mm	
	Power Consumptio	on		536*445*319mm			
	Joint Range			±360°			
	Joint Speed	J1-J4 180°/S J5-J6 200°/S	J1-J4 180°/S J5-J6 200°/S	J1-J4 180°/S J5-J6 200°/S	J1-J2 100°/S J3-J4 150°/S J5-J6 180°/S	J1-J2 100°/S J3-J4 150°/S J5-J6 180°/S	
Robotic	Tool Speed			2m/s			
Arm Parameters	Repeatability	±0.02mm	±0.02mm	±0.02mm	±0.03mm	±0.03mm	
	Degree of freedom			6			
	End I/O port Digital input: 3, digital output: 3, analog input:2						
	Control box I/O port Digital input: 16, digital output: 16, analogue input: 2, analogue output: 2						
	I/O Source			24V 2A			
	Communication TCP/IP, ModbusTCP, Profinet(external conversion), Ethernet/IP (external conversion						
	Programming Graphical programming, remote calling interface						
	IP Classification IP66						
	Collaborative Operation 10 advanced security configuration functions						
-	Main Material Aluminium alloy						
	Working Temperature 0-50°C						
	Power input 200-240V AC, 50-60Hz						
	Cable Cable to control box: 5m, cable to teach pendant: 5m						
	Communication frequency						
Force	e control parameters (optional)	V	ísion parameters (c	optional)	protection (optional)	
Force	control tool flange Forc		Al functions	Imago class	ification object detectio	n Class IP66	

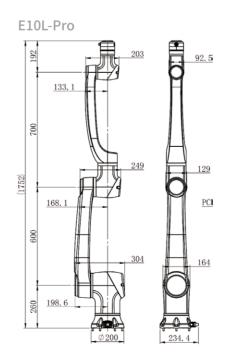
E03-Pro

Drawing



E05L-Pro

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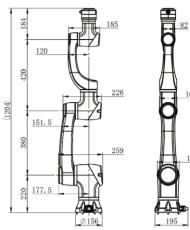


Force control, tool flange Force x-y-z, Torque x-y-z Al functions Image classification, object detection Class IP66 Range 200N,10Nm Application Positioning Precision 2N,0.1Nm 2D,0.2mm Positioning accuracy 4N,0.2Nm 5 megapixels, working distance 100mm~∞ Hand-eye camera Accuracy External vision (optional) Laser sensor or a depth RGBD camera Mini Control Box (Optional) Teach Pendant Control Box Dimensions 445.2mm x 318.8mm x (360+176)mm 323x221x80(mm) 327 mm x 230 mm x (45+22) mm Dimensions Dimensions 2.7kg (Include Cable) Stand Height 176mm Power Input Weight 10.4" 18.5kg I/O Source DC24V Weight 1024 x 800 48V DC Resolution Power Output Inputs 8 , Outputs 8 IP Classification IP20 E-stop Button Working Temperature TCP/IP Modbus IP Classification IP54 Working Humidity 90% Relative Humidity (non-condensing) Communication

IP20

IP Classification

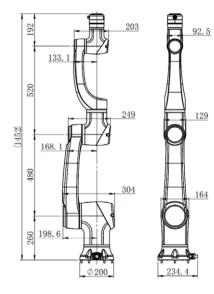
E05-Pro



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129

E10-Pro



S collaborative robot

Overview 概述

Han's Robot S series collaborative robot with high payloads and long arm reach, which can easily handle a super heavy20KG payload and 1300mm~1700mm working radius.It can be widely used in machine loading and unloading, palletizing, assembly and heavy load handling applications. The Han's Robot S15 is a great tool for users to improve their productivity comprehensively, with a qualitative leap in product performance, safety protection, response time and anti-interference capability.

Why S 亮点

Suitable for heavy load scenarios

With a rated load of 15kg~20kg and a ma ximum working radius of 1700mm, it can cover a wide range of compl ex and large load applications



Extremely fast response

End-to-end EtherCAT bus communic ation, compatible with high power sup ply and Gigabit Ethernet, real time co ntrol refresh frequency of 1000/5000 Hz and industry leading control accur acy



Security collaboration

Based on core independent research and development capabilities, it has 10 advanced safety configuration functions such as collision detection, making human-machine collaborat ion more secure and reliable



Very low barrier to entry

Support pad, computer, instructor and other multi-terminal graphical control, 30 minutes to learn to change the progr amming methods, 1 hour to start operati on



Simple customisation and easy deployment

The modular design of the whole mac hine, from the module to the boom, c an meet the individual needs of custo mers, easy to install and dismantle, to achieve flexible deployment and eas y maintenance









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G HAN'S PO

Application

Flexible and customised
production

• Loading and unloading of machine tools

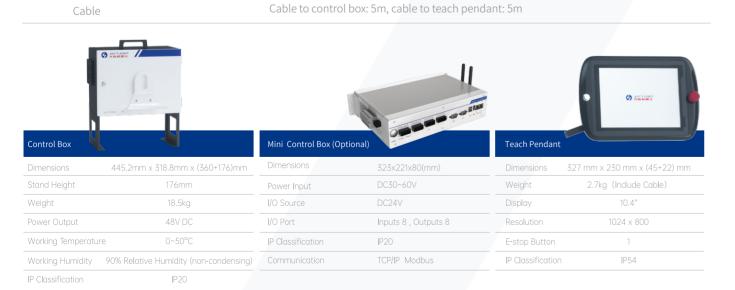
 Production line material handling

• Palletizing and depalletizing

• 3C Manufacturing

• Assembly

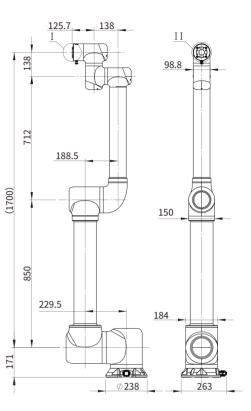
Model 64kg Weight 63kg Payload 15kg 20kg 1300mm Reach 1700mm Power consumption 800W typical application 800W typical application $\pm 360^{\circ}$ $\pm 360^{\circ}$ Joint Range J1-J2 90°/s J1-J2 90°/s Joint Speed J3-120°/s J3-J4 120°/s J4-J6 180°/s J5-J6 180°/s 1.8m/s 1.6m/s Tool Speed \pm 0.1mm ± 0.1 mm Repeatability Degree of freedom 536*445*319mm Control b o x dimension End I/O port Digital input: 3, digital output: 3, analogue input: 2 Control box I/O port Digital input: 16, digital output: 16, analogue input: 2, analogue output: 2 I/O Source 24V 2A Communication TCP/IP and Modbus Graphical programming, remote call interface Programming IP Classification IP54 Collaborative operation 10 advanced security configunation functions Main material Aluminium alloy 0-50°C Working Temperature 200-240V AC, 50-60Hz Power input

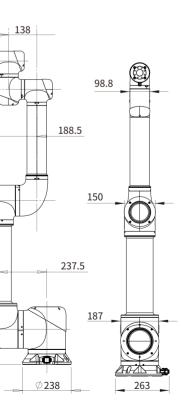


Drawing

S15

S20





Han's Robot Products / Six-axis Collaborative Robots

Elfin-Ex Explosion-proof Collaborative Robots

Overview 概述

Han's Robot introduces the explosion-proof collaborative robots, which have received national certification for explosion protection. It can replace workers and work in explosive hazardous environments to significantly reduce operational risks.

The series adopts a leak-compensated positive pressure explosion-proof system with medium isolation of the ignition source, and the shell is designed with multiple sealing structures, thus realising a compound explosion-proof structure of intrinsic safety and positive pressure; equipped with a positive pressure monitoring system, the positive pressure protection gas pressure of the robot can be monitored in real time and provides power failure protection , blocking explosive combustible gases and dust from entering the robot to avoid the risk of explosion.



Basic Configuration 基础配置





Built-in pressure sensor, positive pressure explosion -proof construction



Intrinsically safe and explosion Positive pressure explosion-proof

Intrinsically safe and explosion-proof



Electric Control Cabinet

Robotic arm control module, explosion-proof cabinet with pressure monitoring system to ensure normal ope ration of the arm in real time and protection against po wer failure in case of pressure abnormalities







• Military production

• Surface coating

• Vehicle refuelling and filling

Civil explosives - transfer of flammable and explosive substances

- Complete vehicle painting
- Powder and paint spraying



1

2

Say "no" to explosions with multiple blast protection

A leak-compensated positive-pressure explosion-proof system with medium isolation of the ignition source is used for reliable sealing performance; the shell is sealed with multiple seals, thus reali sing an intrinsically safe, positive-pressure and other composite explosion-proof structure; equip ped with an air pressure monitoring system for full process detection, reducing the risk of explosi on to zero.

Reliable sealing against water and dust ingress

The robot is designed with a reliable and highly hermetic structure to achieve IP66 level of protection against water and dust.

³ Easy to use, flexible and convenient

No professional knowledge of explosion-proofing and programming is required, even if you have no bas ic knowledge you can easily get started; fast drag-and-drop operation, automatic programming, high intel ligence

4

Full range of models and loads to choose from

The E05F, E10F-L, E10F and E15F models are available in four load options of 5KG, 8KG, 10KG and 15KG to meet the needs of more scenarios and industries.

5

Wide range of applications, easy to expand

Petrochemical industry:

Petroleum refining, hazardous gas transfer, environmental inspections

Painting industry:

Painting and powder coating of metal and plastic surfaces

Service industry:

e.g. automatic refuelling and filling of cars Also suitable for scenarios with a lot of dust and significant liquid splashing

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Low investment, high return

Cost-effective product; virtually maintenan ce-free; low consumables; high yield, high return

• 7

Compact size and light weight

Easy handling and smallfootprint



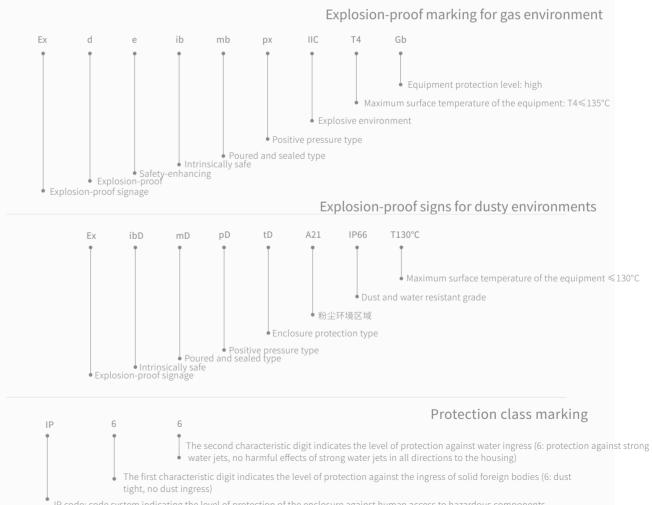


Complies with GB3836/GB12476 national standards Meets the requirements for normal operation in Zone

Certified by the national instrumentation

explosion-proof safety inspection station

- 1 and Zone 2 explosive gas environments and Zone 21 and Zone 22 explosive dust environments
- Can be used for special operations in explosive and combustible dust environments

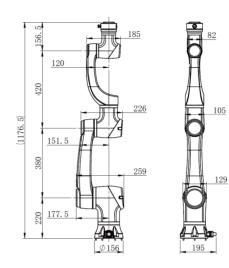


IP code: code system indicating the level of protection of the enclosure against human access to hazardous components, against the ingress of solid foreign bodies or water, and additional information relating to such protection

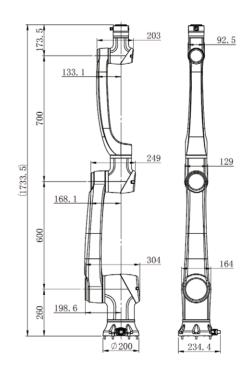


Model	E05F	E10F	E10F-L	E15F	
Weight	25kg	43kg	45kg	60kg	
Payload	5kg	10kg	8kg	15kg	
Reach	800mm	1000mm	1300mm	1300mm	
Joint Range		J1-J6	±360°		
Joint Speed	J1-J4: 180°/s J5-J6: 200°/s	J1-J2: 100°/s J3-J4: 150°/s J5-J6: 180°/s	J1-J2: 100°/s J3-J4: 150°/s J5-J6: 180°/s	J1-J2: 80°/s J3-J4: 120°/s J5-J6: 150°/s	
Maximum tool speed		2n	n/s		
Repeatablity	±0.02mm	±0.03mm	±0.03mm	±0.05mm	
Explosion-proof IP Classification		Ex d e ib mb px IIC T4 Gb Ex ibD mD pD tD A21 IP66 T130°C			
Degree of freedom		6			
Control box I/O port Digital input		t: 16, digital output: 16, analogue input: 2, analogue output: 2			
Communication TCP/IP , Mo		odbusTCP,Profine (t O p t i o n a l),Ethernet/IP (Optional)			
Programming Graphical programming, remote call interface					
IP Classification IP66					
Collaborative operation 10 advanced s e c u r i t y configuration functions					
Main material Aluminium alloy					
Working Temperature		0-5			
Power input 200-240V AC, 50-60Hz					
able Maximum length customizable 15-20m					

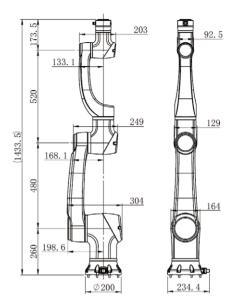
E05F



E10F-L

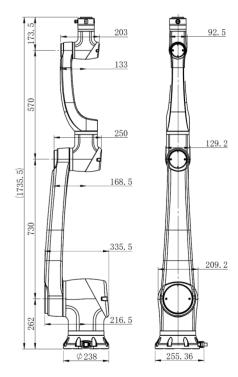


E10F



E15F

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Han's Robot Products/Automated Guided Vehicle

FR Multi-sensing Autonomous Vehicle

Overview

Dimensions

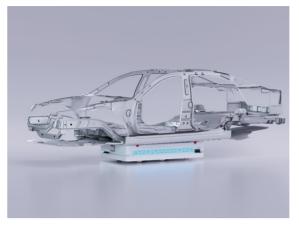
FR-200 200kg 46AH

FR-1200 1200kg 125AH

FR is a new generation of multi-sensing autonomous vehicles from Han's Robot, used for indoor intralogistics tasks. It can autonomously transport items and navigate freely in its environment. As a mobile robot, it makes the labor of the workers easier and improves business efficiency. This robot is also equipped with obstacle avoidance radar, which can work continuously and safely without interruption. Moreover, it has built-in autonomous navigation system and dispatching software, which enable multiple FR to serve simultaneously, keep the production running and maintain the flexibility of its manipulation.

i 230mm



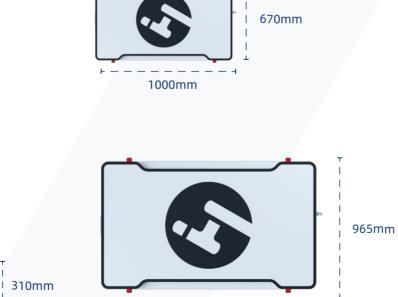


Features

Payload 200kg / 1200 kg







1530mm



Artificial Intelligence Path Optimization, Smart Interaction



Safe Human Detection Touchless Sensor Technology



High speed charging and long endurance



3D Visual Sensor (optional)



Status Visualization

LED lights can show the robot'sworking status



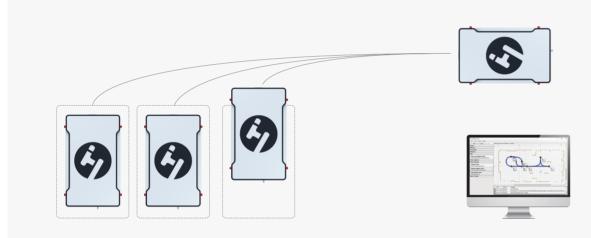


FR+Elfin-P

FR for Logistics



FR+Elfin



Intelligent Fleet Management: Formation Driving and Dynamic Planning

Recommended Industries







Tech specs

	Model	FR-200	FR-1200			
	Payload	200 kg	1200 kg			
	Actuation	Differenti	al Drive			
	MAX Velocity	1.5 m	n/s			
	Communication Interface	TCP/IP , Modbus				
	Outbound Interface	WiFi,1>	KRJ45			
Basic barameters	IP Classification	IP5	4			
_	Weight (100/120) kg(without / with lifting units)	(280/310) kg(without / with lifting units)			
	Dimensions	L1000×W670×H230(mm)	L1530×W965×H310(mm)			
	Positioning Accuracy	±10mm				
	Safety Laser Scanner 360°	° PLd/ Category 3 (ISO 13849– 1)				
	Navigation Mode	Laser SLAM				
_	Lifting Units	1x200kg ,1 x 0-60mm	4x400kg,4x0-50mm			
	Battery Voltage	DC 4	DC 48V			
	Battery Capacity	46AH	125AH			
Battery	Charging Voltage	AC220V, 50-60Hz				
arameters	Charging Time	2hrs (Automated) / 1.5hrs(Manual)	2.5hrs (Automated) / 2hrs(Manual)			
	Running Time (no load)	8h	12h			
	Charging Mode	Automated / Manual				
Soncor	Vision (optional)	RealSense – D415 Camera				
Sensor –	Safety	Touchless Safe Human Detection Safety Scanners				
	Operating Software	g Software Robot application software / Dispatching software				
Software	Open Architecture	AGV	AGV API			
	Safety Features	Safe Human Detection	n Detection, Safe Speed Control			
ogramming	Human-Robot-Interaction	Motion tracking,	PC based GUI			
Features	Environment Visualization	Dynamic Mapping (SLAM)				
-	Fleet Management	Formation Driving, Fle	eet Monitoring Tool			
Others	Warranty	12 months				

Healthcare

Logistics

3C

Han's Robot Products/Mobile Manipulator

STAR Mobile Manipulator

Overview

The STAR mobile manipulator is an intelligent mobile robot, which combines the self-developed mechanical arm and mobile robot FR, vision system, gripper and other components to perform mobile operations to achieve functional applications such as grasping, handling, assembly, and detection of materials. According to the customer's on-site use environment, it can match the corresponding scheduling system for flexible scheduling and rapid deployment. The core units of the STAR are independently developed, with high cost performance and strong system scalability, which can connect to the customer's MES (or other systems) and provide rich solutions according to different needs of customers. It can serve the future intelligent manufacturing industry 4.0.

It is mainly used in industries (such as electronics, metal products, auto parts, electricity, new energy, ships, aerospace), healthcare, family services, file management and other applications.



Intelligent scheduling

Based on the self-developed architecture and intelligent planning algorithm, the large-scale scheduling of robots is realized to ensure the efficient operation of the system.



Stable performance

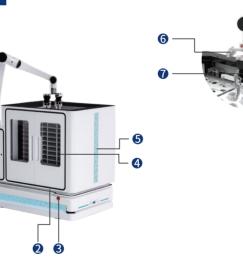
With independent development of core components, it shows the perfect combination of body and arm, and the performance is more stable.

Automatic lifting

requirements.

The internal materials are automatically lifting, which can maximize the use of body space, store more materials in a limited space, and reduce material transfer.

Parts name



E-STOP **1 8 9 10 1** Drainage Outlet 2 Lifting Unit 1 (To Be Processed)

Singal Lights 5 3D Camera 6 Electric Gripper 🛛 🕐

Features

Rapid Deployment

Based on the SLAM navigation technology, without the scene transformation, the environment map is automatically generated, the scheduling planning service is realized, and the deployment is fast.



Self-check

It can obtain the robot hardware and operating status in real time, which realizes self-check and fast fault diagnosis.

F

Automatic charging

The STAR can automatically go back to charging pile for recharging, which ensures the robot to achieve 7*24 all-day operation and high-frequency fast response between tasks.

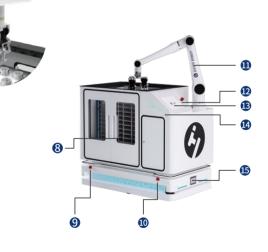


Strong Scalability

It efficiently connects to the enterprise's MES/WMS information system and can quickly install application function modules according to

Intelligent obstacle avoidance

Equipped with sensors such as lidar and visual camera (optional), it can intelligently identify obstacles, actively park and avoid obstacles.



8	Lifting Unit 2 (Finished Product)	14
1	E10-L (Optional)	
₿	12" Touchscreen	
ß	ED	

Model	STAR-S	STAR-L	STAR-M	STAR-H		
Vehicles	HR150	HR300	HR600	HR1200		
Robot	E03/E05	E03/E05/E05-L/E10	E05-L/E10/E10-L/E15	6 E05-L/E10/E10-L/E15		
Dimensions (Elfin Not Included)	700*500*630(mm)	950*650*900(mm)	1200*700*900(mm)	1530*965*1300(mm)		
Actuation	Differential Drive	Differential Drive	Steering Wheel	Differential Drive		
Tray Lifting Unit		Custon				
MAX Velocity	1.5m/s	1.5m/s	1.1m/s	1.5m/s		
Navigation Mode Laser SLAM, Hybrid Navigation (Fusion Vision) (Optional)						
Vision (Standard Mode) Camera (Customizable)						
Positioning Accuracy ±0.5mm						
Operating Software Han's Robot application software / Dispatching software (optional)						
Development Platform Windows/Linux						
Battery Voltage		DC)C 48V			
Running Time (with load)	>6h	>10h	>12h	>12h		
Charging Time	≤2 hours	≤2 hours	≤2 hours	Manual Charging≤2.5 hours		
Standard Communication I	nterface	TCP/IP, H	TTP, SDK			
Outbound Interface		12 M				
	Vehicles Robot Dimensions (Elfin Not Included) Actuation Tray Lifting Unit MAX Velocity Navigation Mode Vision (Standard Mode) Positioning Accuracy Operating Software Battery Voltage Running Time (with load) Charging Time	VehiclesHR150RobotE03/E05Dimensions (Elfin Not Included)T00*500*630(mm)ActuationDifferential DriveActuationDifferential DriveTray Lifting Unit1.5m/sMAX Velocity1.5m/sNavigation ModeLassVision (Standard Mode)1.5m/sPositioning AccuracyHan's RefOperating SoftwareHan's RefBattery VoltageStandard Mode)Running Time (with load)>6hStandard Communication Interface	VehiclesHR150HR300RobotE03/E05E03/E05/E05-L/E10Dimensions (Elfin Not Included)700*500*630(mm)950*650*900(mm)ActuationDifferential DriveDifferential DriveActuationDifferential DriveDifferential DriveMAX Velocity1.5m/s1.5m/sNavigation ModeLaser SLAM, Hybrid NavigatVision (Standard Mode)Camera (CuPositioning Accuracy±0.5Development PlatformWindowBattery VoltageDCRunning Time (with load)>6h>10hStandard Communication InterfaceTCP/IP, H	VehiclesHR150HR300HR600RobotE03/E05E03/E05-L/E10E05-L/E10/E10-L/E10Dimensions (Elfin Not Included)700*500*630 (mm)950*650*900 (mm)1200*700*900 (mm)ActuationDifferential DriveDifferential DriveSteering WheelActuationDifferential DriveIsferential DriveSteering WheelMAX Velocity1.5m/s1.1m/s1Navigation ModeLaser SLAM, Hybrid Navigation Vision (Ottor1Vision (Standard Mode)Camera (Custorrizable)1Positioning Accuracy±0.5m/s1Poselopment PlatformWindows/LinuxBattery VoltageDC 48VRunning Time (with Ioad)>6h>10hStandard Communication InterfaceTCP/IP, HTTP, SDK		



† Industry applications:

Han's Robot collaborative robots have been widely used in electronics, automotives, semiconductors, metal processing, new energy, pipeline inspection and other fields. Han's Robot uses robot technologies for collaboration in global intelligent manufacturing, which promotes productivity in all walks of life.





↓ Process applications:

Loading and unloading, welding, marking, assembling, polishing, handling, inspecting, gluing, picking, screwing, etc.

Electronics manufacturing industry

Laser cutting

One robot is used for loading and unloading for four laser cutting machines at the same time. The four cutting machines are placed in pairs, and a 7-axis guide rail is used in the middle to realize the motion of the collaborative robot between the machines. A vision camera is integrated to the robot to realize the positioning for loading and unloading as the required unloading precision of the laser cutting machine is about 0.1 mm.

Space-Saving

Easy to operate

The overall layout is compact which occupies a small area, and there is no need to do

It is easy to operate the collaborative robots. Customers can switch products or debug new products by themselves great changes to the original after simple training, which greatly plant. Moreover, the equipment reduces the cost of product replacement.

More scenarios: loading and unloading, inspecting, grinding, spraying, assembling, marking, etc.

Automotive manufacturing industry

Gluing for car lights

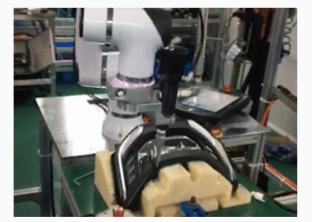
By adopting one-to-two structure integration, one cold glue device supplies can glue for two collaborative robots. The double-station free gluing improves the gluing efficiency and quality and avoids the impact on the personnel health, which greatly reduces labor and equipment costs.

Safe and flexible

High-precision linear gluing, harmless operation improved yield rate.

The cold glue does not require heating, which greatly reduces energy consumption.

Energy saving and low consumption



More scenarios: loading and unloading, spraying, assembling, inspecting, picking, marking, etc.



Healthcare industry

Orthopaedic drilling and nail

The orthopaedic drilling and stapling robot, in conjunction with the optical positioning system and other equipment, achieves a more int elligent and reliable surgical plan, a more precise and humane surgi cal execution, and an improved level of service in orthopaedic drilli ng and stapling surgery.

Accuracy: The robot can be positioned with an accuracy of up to 0. 02 mm, enabling precise reproduction of the position and force of the bi llion dollar operation, ensuring precise and accurate surgery.

Safety: The safety of human-machine collaboration is ensured through advanced safety functions such as collision protection, motion area rest riction and check pressure protection; at the same time, surgical safety is guaranteed based on the advantages of high precision and high sensit ivity

Humanisation: Soft movement control and real-time pressure tracking control for expert-like results and reduced patient stress

Efficiency: The robot is stable, safe and easy to use and can perform continuous surgery

Hybrid robot

CNC loading and unloading

In this case, the mobile manipulator moves intelligently in the same workshop to support multipleproduction links:

CNC production workshop material transfer project Automatic loading and unloading items of materials

Case features

Han's robot 6-axis collaborative robot + intelligent mobile robot, with its large capacity and automatic lifting mechanism, can load more materials at one time, freely shuttle in the workshop, ensure the normal operation of multiple equipment in the workshop, and help customers to automate production needs.

More scenarios: warehousing, packaging, assembling, testing, pickup, etc.



More scenarios: Piercing



Metal processing Laser Marking industry

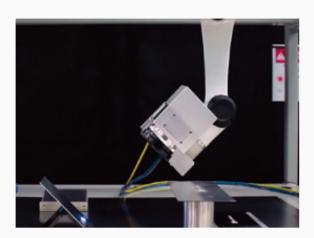
Han's marking robots can realize multi-directional automatic marking, from loading and unloading to marking, which meets the unmanned, automated, and flexible use requirements, improves the delivery efficiency, and reduces production costs.

Flexible and efficient Easy to operate

Realize flexible, efficient, multi-angle, multi-material free marking.

Graphical programming and robot program editing are simple and easy.

More scenarios: marking, rust removal, grinding, screwing, welding, etc.



Sanitary industry

Spin welding

Solve the pain points of ultrasonic welding with high noise and inconsistent manual feeding pace Less labor and higher efficiency, easy to operate, stable robot production.

More scenarios: visual grasping, gate polishing, assembling, picking and placing, hot plate welding, loading and unloading, etc.

Semiconductor Industry

Wafer handling

Han's hybrid robots interwork with wafer processing equipment to provide MES whole-factory automated wafer handling solutions, and fully independent IPR upper-computer scheduling system and planning.

Fast and robust

One robot is connected to five wafer processing devices for loading and unloading, and the efficiency is 68% higher than manual operation. The fully automated black light factory works automatically in a controllable manner. Multiple devices can be independently scheduled in 24-hour operation



More scenarios: lithography, cleaning, etching, precipitation, equipment care, grinding, etc.

Pipeline inspection industry

Pipeline equipment inspection

In this application, Han's Robot is integrated with various sensors to realize 24-hour visual automatic inspection in the pipeline. The 6-DOF joint design allows the robot to be better planned for complex motion paths, increases the monitoring scope and precision, and achieves no-blind-angle monitoring.

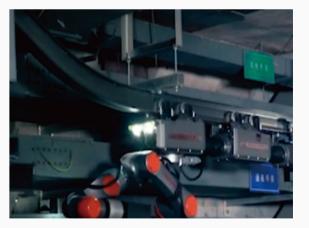
Diverse applications Less risks

Used in power, energy, petroleum, transportation, smart buildings, etc.

Less safety risks and labor costs compared with traditional manual inspections

More scenarios: electricity, energy, construction, transportation, minerals, marine





Education industry

VR training

1. VR industrial robot task training system based on virtual reality. It realizes multi-brand, multi-robot, multi-scene robot task operation training, including robot welding training, robot spraying training, robot casting training, robot palletizing training, robot loading and unloading training, and robot mobile phone assembly training. 2. Learn and master the operations of industrial robots through the VR robot system, and practical training of physical collaborative robots, which further deepens and consolidates the basic knowledge and skill training results of industrial robots, and greatly improves the teaching and training effects.





More scenarios: teaching platform, cyclic assembly line, mobile robot application, SCARA application, laser marking robot loading and unloading workstation, disassembly and installation of collaborative robot, robot integrated standard workstation

New retail industry Milk tea robot

In this application, a new tea flagship store uses Han's robots in the beverage production area to collaborate in tea making, blending, and delivery, which adds value (such as freshness, attractiveness, and customer experience) to its service and image and greatly speeds up beverage production.

Fresh experience

One-click self-service, widely used in airports, hotels, restaurants, stations, shopping malls, and other places



Less labor and higher efficiency, easy operation, convenient maintenance, short time period of cost recovery



More scenarios: massage, coffee latte, unmanned sales, etc.

